

Torque Sensor

Rotating, contact ring transfer

Model 86403 with square end Model 86413 with round shaft ends Model 86423 with hexagonal shaft end Code: 86403 EN

Delivery: 4 weeks

Warranty: 24 months







- Measuring ranges between 0 ... ± 1 Nm and 0 ... 1000 Nm
- Excellent reproducibility
- Standardized output signal makes exchange easy
- Optionally available with factory calibration certificate
- Designed for clockwise and counterclockwise torque
- Optionally available with integrated angle measurement
- Rotation speed up to 3000 min⁻¹ (short-term)

Application

Precise, reliable measurements of both static and dynamic torques in either direction can be made with this range of sensors.

This opens a wide range of possible applications to the user. These torque sensors are standard equipment in a wide range of industrial automation, quality control and automotive components industry applications, as well as in laboratories.

Typical applications:

Screwing technology

- Checking and adjusting bolting tools such as torque limiting wrenches, screwdrivers
- ► Testing bolted connections

Measuring the drag torque of motors and pumps

- ► Frictional torques of gears, bearings and seals
- Testing torsion springs
- Adjusting equipment in the automobile industry (sunroof, power windows etc.)

Description

Strain gauges are mounted on the torsion shaft of the sensor element, itself made of steel, connected to form a full bridge. The electrical power excitation for the wire strain gauge full bridge and the transmission of the measured signal is provided through a high-quality slip-ring system between the stator and the rotor.

For a clockwise torque, the measurement signal is positive, and it is negative for a counterclockwise torque.

The sensor for the optionally available angle measurement for the square shaft versions is fitted with an additional pulse-generating disk.

With the aid of a second encoder track, displaced by 90°, allows the subsequent evaluation units to perform 4-fold edge evaluation. This allows significantly improved resolution to be achieved. The offset track makes it possible to detect the direction of the rotation.

The characteristic parameters for the sensors are standardized in order to reduce the effort required to check a connected amplifier or to exchange the sensor.

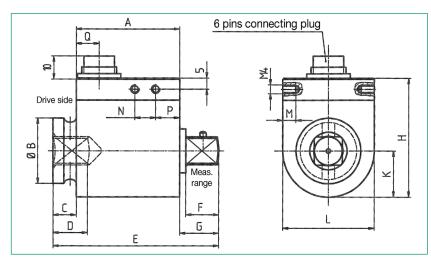
Technical Data Model 86403

Toque sensor, rotating, standard square ends according to DIN 3121

Order Code		urement ange	Sensi- tivity	Square Ends	Constant	Max. Lat- eral Force	Torque of Inertia Drive End	Mass					Di	men	sions	s [m	im]					
			[mV/V]		[Nm/rad]		J in [kg m²]	[kg]	Α	В	С	D	Е	F	G	Н	L	ĸ	М	N	Р	Q
86403-5001	0 ±	1 Nm	0.5	1/4"	1.9 · 10 ²	4	2.9 · 10 ⁻⁷	0.14	45.5	13	8.6	8	64	7.2	9.9	39	24	12	5	9	8.6	12.2
86403-5002	0 ±	2 Nm	0.5	1/4"	4.3 · 10 ²	5	2.9 · 10 ⁻⁷	0.14	45.5	13	8.6	8	64	7.2	9.9	39	24	12	5	9	8.6	12.2
86403-5005	0 ±	5 Nm	2	1/4"	$2.7 \cdot 10^{2}$	7	2.9 · 10 ⁻⁷	0.14	45.5	13	8.6	8	64	7.2	9.9	39	24	12	5	9	8.6	12.2
86403-5012	0 ±	12 Nm	2	1/4"	6.6 · 10 ²	7.5	3.0 · 10 ⁻⁷	0.14	45.5	13	8.6	8	64	7.2	9.9	39	24	12	5	9	8.6	12.2
86403-5025	0 ±	25 Nm	2	3/8"	$2.3 \cdot 10^{3}$	12	1.2 · 10 ⁻⁵	0.32	47.5	22	10.1	12.2	71	10.4	13.5	54	42	21	6	9.5	11	10.5
86403-5063	0 ±	63 Nm	2	3/8"	5.7 · 10³	28	1.2 · 10 ⁻⁵	0.32	47.5	22	10.1	12.2	71	10.4	13.5	54	42	21	6	9.5	11	10.5
86403-5160	0 ±	160 Nm	2	1/2"	1.4 · 10 ⁴	65	1.7 · 10 ⁻⁵	0.35	47.5	29.7	10.7	15.9	76	15.1	17.9	54	42	21	6	9.5	11	10.5
86403-5500	0 ±	500 Nm	2	3/4"	5.9 · 10 ⁴	200	1.1 · 10 ⁻⁴	0.80	55	44	19.1	24.9	100	22.6	25.9	68	60	30	-	-	-	10.5
86403-6001	0 ±	1000 Nm	2	1"	1.1 · 10 ⁵	240	2.6 · 10-4	1.40	55	54	33.1	29.6	132	27.4	43.9	68	60	30	-	-	-	10.5

Higher ranges on request

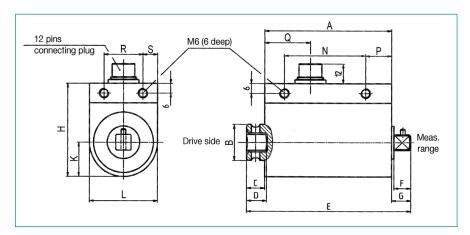
Dimensional drawing Model 86403



Model 86403-...-V501
Torque sensor, rotating, standard square ends, with angle measurement

Order Code	Measi	urement	Sensi-	Square	Spring	Max.	Torque of	Mass						Dim	ensi	ons [mm]						
	R	ange	tivity	Ends	Constant		Inertia																	
							Drive End																	
						Force		r			ء ا	۱ ـ	۱ _	ı _	۱ ۵	١		٠. ١	اءا					
			[mV/V]		[Nm/rad]	[N]	J in [kg m²]	[kg]	Α	В	С	D	Е	F	G	Н	L	K	M	N	Р	Q	R	S
86403-5001-V501	0 ±	1 Nm	0.5	1/4"	1.4 ·10 ²	4	3.2 ·10-6	0.5	65	13	9	8	84	7.2	10	48.5	34	17	4	9	10.5	30.5	10	12
86403-5002-V501	0 ±	2 Nm	0.5	1/4"	4.5 ·10 ²	5	3.3 ·10-6	0.5	65	13	9	8	84	7.2	10	48.5	34	17	4	9	10.5	30.5	10	12
86403-5005-V501	0 ±	5 Nm	2	1/4"	3.0 ·10 ²	7	3.3 ·10-6	0.5	65	13	9	8	84	7.2	10	48.5	34	17	4	9	10.5	30.5	10	12
86403-5012-V501	0 ±	12 Nm	2	1/4"	6.7 ·10 ²	7.5	3.3 ·10-6	0.5	65	13	9	8	84	7.2	10	48.5	34	17	4	9	10.5	30.5	10	12
86403-5025-V501	0 ±	25 Nm	2	3/8"	2.4 ·10 ³	12	1.2 ·10-5	0.5	78	22	11	12.2	100.8	10.4	11.8	57	42	21	6	50	16	28	24	9
86403-5063-V501	0 ±	63 Nm	2	3/8"	6.8 ·10 ³	28	1.2 ·10-5	0.5	78	22	11	12.2	100.8	10.4	11.8	57	42	21	6	50	16	28	24	9
86403-5160-V501	0 ±	160 Nm	2	1/2"	1.2 ⋅10⁴	65	1.7 ·10-5	0.6	78	29.8	12	16.9	106	15.1	16	57	42	21	6	50	16	28	24	9
86403-5500-V501	0 ±	500 Nm	2	3/4"	3.9 ⋅10⁴	200	9.2 ·10-5	1.3	92	44	18	24.9	135	22.6	25	70	56	28	10	66	13	43	24	16
86403-6001-V501	0 ±1	000 Nm	2	1"	8.9 ⋅10⁴	240	3.6 ·10-4	1.5	92	54	53.1	29.9	177	27.3	31.9	70	56	28	10	66	13	43	24	16

Dimensional drawing Model 86403-...V501



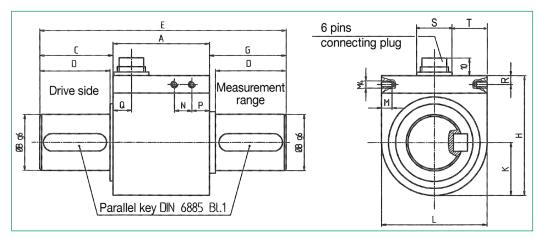
Technical Data

Model 86413

Torque sensor, rotating, round shaft ends with parallel key

Order Code	Measurement	Sensi-	Spring	Max.	Torque	Mass					[Dimer	nsior	ns [m	ım]					
	Range	tivity	Constant	Lat-	of Inertia															
				eral	Drive End															
				Force			١.	1												
		[mV/V]	[Nm/rad]	[N]	J in [kg m²]	[kg]	Α	В	С	D	E	G	Н	L	K	М	N	Р	Q	R
86413-5001	0 ± 1 Nm	0.5	1.9 ·10 ²	4	1.34 ·10 ⁻⁶	0.16	45.5	8	19.7	18	85	19.7	39	24	12	5	9	27.9	33.3	5
86413-5002	0 ± 2 Nm	0.5	1.9 ·10 ²	5	1.34 ·10 ⁻⁶	0.16	45.5	8	19.7	18	85	19.7	39	24	12	5	9	27.9	33.3	5
86413-5005	$0 \dots \pm 5 \text{ Nm}$	2	2.43 ·10 ²	7	1.34 ·10 ⁻⁶	0.16	45.5	8	19.7	18	85	19.7	39	24	12	5	9	27.9	33.3	5
86413-5010	0 ± 10 Nm	2	4.56 ·10 ²	7.5	1.35 ·10 ⁻⁶	0.16	45.5	8	19.7	18	85	19.7	39	24	12	5	9	27.9	33.3	5
86413-5020	$0 \dots \pm 20 \text{ Nm}$	2	1.77 ·10 ³	12	1.16 ·10 ⁻⁵	0.35	47.5	15	21.1	20	90	21.5	54	42	21	6	9.5	11	10.5	5
86413-5050	$0 \dots \pm 50 \text{ Nm}$	2	4.82 ·10 ³	28	1.17 ·10 ⁻⁵	0.38	47.5	15	21.1	20	90	21.5	54	42	21	6	9.5	11	10.5	5
86413-5100	$0\;\pm 100\;Nm$	2	9.85 ·10 ³	65	1.25 ·10 ⁻⁵	0.42	47.5	18	24	22	95	23.6	54	42	21	6	9.5	11	10.5	5
86413-5200	$0\;\pm200\;Nm$	2	2.80 ·10 ⁴	80	9.15 ·10 ⁻⁵	0.90	55	32	41.6	40	140	43.4	68	60	30	-	-	-	10.5	5
86413-5500	0 ± 500 Nm	2	6.33 ⋅10⁴	200	9.42 ·10 ⁻⁵	0.90	55	32	41.6	40	140	43.4	68	60	30	-	-	-	10.5	5

Dimensional drawing Models 86413 and 86413-...V501



Model 86413-...V501 Torque sensor, rotating, round shaft with keyways and internal angle measurement

Order Code	Measure	ement		Spring	Max.	Torque of	Mass						Dim	ensio	ons [mm]						
	Rang	ge	tivity	Constant		Inertia																
					eral	Drive End																
					Force					1			1		1	1	١		۱ ـ		1 -	
			[mV/V]	[Nm/rad]	[N]	J in [kg m²]	[kg]	Α	В	C/G	D	E	Н	L	K	М	N	Р	Q	R	S	T
86413-5001-V501	0 ±	1 Nm	0.5	2.3 ·10 ²	4	3.3 ⋅10-6	0.5	65	10	17.5	15.5	100	48.5	34	17	4	9	10.5	30.5	6.5	20	7
86413-5002-V501	0 ±	2 Nm	0.5	2.3 ·10 ²	5	3.3 ·10 ⁻⁶	0.5	65	10	17.5	15.5	100	48.5	34	17	4	9	10.5	30.5	6.5	20	7
86413-5005-V501	0 ±	5 Nm	2	2.9 ·10 ²	7	3.3 ·10⁻ ⁶	0.5	65	10	17.5	15.5	100	48.5	34	17	4	9	10.5	30.5	6.5	20	7
86413-5010-V501	0 ± 1	0 Nm	2	5.6 ·10 ²	7.5	1.1 ·10 ⁻⁵	0.5	65	10	17.5	15.5	100	48.5	34	17	4	9	10.5	30.5	6.5	20	7
86413-5020-V501	0 ± 2	0 Nm	2	1.6 ·10 ³	12	1.1 ⋅10-5	0.6	78	15	21	20	120	57	42	21	6	50	16	28	6	20	11
86413-5050-V501	0 ± 5	0 Nm	2	4.1 ·10 ³	28	1.1 ·10 ⁻⁵	0.6	78	15	21	20	120	57	42	21	6	50	16	28	6	20	11
86413-5100-V501	0 ± 10	00 Nm	2	7.9 ·10³	65	1.3 ⋅10-5	0.6	78	18	25	24	128	57	42	21	6	50	16	28	6	20	11
86413-5200-V501	0 ± 20	00 Nm	2	2.8 ⋅10⁴	80	1.0 ·10 ⁻⁴	1.3	92	32	44	40	180	70	56	28	10	66	13	43	6	20	18
86413-5500-V501	0 ± 50	00 Nm	2	5.3 ⋅10⁴	200	1.0 ·10-4	1.3	92	32	44	40	180	70	56	28	10	66	13	43	6	20	18

Model 86423 Torque sensor, rotating, standard hexagonal shaft ends 1/4" DIN 3126 Form E/F

•			
Order Code	Measurement	Sensi-	Mass
	Range	tivity	
		[mV/V]	[kg]
86423-5001	0 ± 1 Nm	0.5	0.2
86423-5002	0 ±2 Nm	1	0.2
86423-5005	0 ± 5 Nm	1	0.2
86423-5010	0 ± 10 Nm	2	0.2
86423-5020	0 ± 20 Nm	2	0.2

The CAD drawing (3D/2D) for this sensor can be imported online directly into your CAD system.

Download via www.burster.com or directly at www.traceparts.com. For further information about the burster traceparts cooperation refer to data sheet 80-CAD-EN.

Model 86423 Model 86423 Meas. range 1/4" hexagon DIN 3126 (ISO 1173) Version E/F - quick-action chuck 965-02

- Drive end --- hexagon head
- ▶ Measurement side --- hexagon socket
- Quick-action chuck

Note: The max. allowed static lateral force is smaller than 10 % of the lower value of the measurement range.

General Technical Data for all Sensors

Electrical values

Torque sensor

Bridge resistance (full bridge): 350 O Excitation voltage: 2 ... 12 V DC

Characteristic: standardized 0.5 mV/V. 1mV/V or 2 mV/V (refer to tables)

Tolerance of characteristic:

 \pm 0.1 %

Test (option):

If the full bridge is connected to the positive strain gauge excitation voltage, it generates an electrical signal equivalent to 100 % of the nominal signal.

Angle displacement sensor (refer to options)

Excitation voltage: 5 V DC Angle displacement measurement: 360 pulses/rotation 2 TTL outputs with two encoders, angle displacement 90° for detection of direction.

Environmental conditions

±10 °C ... + 60 °C Range of operation temperature: ± 5 °C ... + 50 °C Range of nominal temperature:

Influence of temperature in range of nominal temperature:

to zero signal ±0.01 % F.S./K to characteristic ±0.003 % F.S./K

Mechanical values

Measurement error, consisting of non-linearity

 \leq ± 0.1 % F.S. and hysteresis Relative spread in unchanged mounting position: \leq ± 0.05 % F.S. Range of rotation:

an exceedance of the max. rotary speed, up to 1.5 x max. rotary speed, is possible only for short time

max. rotary speed for

ranges from von ≤0 ... 12 Nm 20001/min ranges from 0 ... 25 Nm to 0 ... 160 Nm 15001/min 0 ... 500 Nm to 0 ... 1000 Nm 1000¹/min ranges from 0 ...2000 Nm to 0... 5000 Nm 5001/min ranges from

Max. operation torque: 120 % of nominal torque Dynamic torques (peak-peak): max. 70 % of nominal torque Limit torque (static): 130 % of nominal torque Breakaway torque (static): 250 % of nominal torque

Angle displacement at nominal torque: $< 0.5^{\circ}$ Material: high strength heat-treated steel, similar to 1.2826 or 12738 Protection class: acc. to EN 60529 IP50

Dimensions: refer to table and dimensional drawing Maintenance/cleaning (contact ring abrasion, recommended change of the brushes): after approx. 5 x 107 rotations

Mechanical connection:

model 86403 Internal and external square acc. to DIN 3121, used for connection to assembling tools for bolt and nuts.

model 86413 Version with keyways on both shaft ends (2 x 180 °) acc. to DIN 6885 page 1

model 86423 Hexagon head and socket 1/4", acc. to

DIN 3126 (ISO 1173) version E/F quick-action chuck

Electrical connection:

Sensors without measurement of angle displacement

Mating connector model 9953 6 pin plug-in connection

Wiring:

1 excitation negative 2 excitation positive 3 shield (not connected in the sensor) 4

positive for clockwise torques 5 output signal negative for clockwise torques

6 100 % check

Sensors with measurement of angle displacement

Mating connector model 9940 12 pin plug-in connection Wiring:

(0 V DC) excitation negative for torque excitation positive for torque (2 ... 12 V DC)

В output signal positive for clockwise torque D output signal negative for clockwise torque

(0 V DC) excitation negative for angle displ. F excitation positive for angle displ. (+ 5 V DC)

(TTL pulses) G angle output 1 Н angle output 2 (TTL pulses)

angle output (0 V DC)

K check, shunt calibration (option)

NC shield

Order Information

Torque sensor, rotating, square end measurement range 0 ... 1 Nm Model 86403-5001

Torque sensor, rotating, square end, with meas. of angle displ. Model 86403-5063-V501 measurement range 0 ... 63 Nm

Accessories

for sensors without measurement of angle displacement

Mating connector 6 pin, in scope of delivery Model 9953 Mating connector 6 pin, 90° outlet Model 9900-V589

Connection cable, one end open,

Model 99553-000A-0110030 lenath 3 m

Connection cable to burster desktop devices with

12 pin panel jack, length 3 m Model 99141-553A-0150030

Connection cable to 9235 and 9310

Model 99209-553A-0110030 lenath 3 m

Cable adapter to 9163-V3XXXX

length 0.2 m Model 99209-609A-0090002

for sensors with measurement of angle displacement

Mating connector 12 pin, in scope of delivery **Model 9940** Mating connector 12 pin, 90° outlet Model 9900-V539 Connection cable, one end open, Model 99540-000K-0270030 length 3 m Connection cable to model 9307, length 3 m Model 99163-540C-0270030

Strain gauge simulator **Model 9405**

The sensor will be replaced by the strain gauge simulator for checking amplifiers or indicators.

Supply units, amplifiers and process control units like modular amplifiers models 9243, 9206, 9163 or 9307

refer to section 9 of the catalog.

Options

Higher measurement ranges on request.

Manufacturers Calibration Certificate (WKS)

Calibration of a torque sensor with or without amplifier / indicator (measurement chain) in clockwise or / and counter clockwise direction in increments of 20 % of the measurement range.

Mounting Instructions

The sensors, particularly those with small measuring ranges, must be mounted carefully. It is important that the drive and measuring ends are not reversed during assembly. The slip-ring rotation transmitter is located on the drive side. If fitted incorrectly (measuring side and drive side swapped), its friction, which is unavoidable, will be included in the measurement.

The correct position of the measuring side is indicated on the corresponding dimensional drawing. The measuring shaft should always be cleaned prior to assembly and should be supported during fitting, to ensure that no foreign objects are sticking to it. It is recommended that the sensor is electrically connected and that the output signal is watched at the time of fitting. Vibrations originating in the equipment should be kept away from the sensor. The sensor should only be mounted on the coupling after the parts have been accurately aligned. This should be done without free play or lateral forces. It is recommended that the cable connection points upwards, so that abrasion dust cannot fall onto the brush connections.